Application of Anomaly Detection Methods in the Housing and Utility Infrastructure Data

FRCCSC RAS

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# Outline

#### Internet of Things and predictive maintenance

#### Experimental Setup

- Types of equipment
- Proposed system architecture
- Experimental setup
- Data collection protocol

#### Fault detection models

- Student's t-test and its applications
- The two-sampled Kolmogorov-Smirnov test
- Hidden Markov Model in anomaly detection

#### Results and discussion

# Machine condition monitoring

- The Internet of Things concept development in recent years:
  - Hardware items become equipped with means of interaction with each other or with the environment
  - Growing popularity of home sensor technology, which is becoming cheaper
  - Modern tools for data collection, storage and analysis
- Predictive maintenance system goals:
  - Support timely and effective maintenance of in-service equipment
  - Register and identify equipment problems in real time scenario

This work is carried out as part of a project that is aimed at development of software solutions for a housing and utility condition monitoring system.

#### Purpose of this study:

- To introduce the experimental dataset on housing and utility infrastructure equipment faults
- To propose a fault detection system based on statistical and probabilistic approaches

# Housing and Utility Infrastructure Elements



power transformer





pump

heater







gas boiler

HVAC

controller installation

## System Architecture



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## **Experimental Setup**

Hardware sensors were installed on the following elements of housing infrastructure:

- electric heater with current and temperature sensors
- air conditioner with current, temperature and acoustic noise sensors
- ventilation blower fan with anemometer, acoustic noise and current sensors
- power transformer with input/output current, voltage and temperature sensors
- gas boiler system with current, temperature, acoustic noise, leakage and flow sensors
- water pump with current and flow sensors
- lamp with light and current sensors

#### **Experimental Dataset**

The dataset used in this study was collected from abovementioned eperimental setup:

- Sensors were connected to hardware and software controllers
- Readings were obtained every 4 minutes, preprocessed and stored in time series DB
- Measurements were collected during one month
- Equipment went through a series of controlled simulations of various faults and breakdowns
- Every fault type was carefully analyzed, the measurements were used to fit anomaly detection models.

The preprocessing step includes:

- Missing value interpolation (linear, moving average)
- Flag and consistency check

## Fault detection models: Student's t-test

In some fault types, a simple t-test provides acceptable results, i.e. in the ventilation clogging.



Figure 1: Airflow and vibration readings of a ventilation blower fan

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## Applications of Student's t-test

Student's t-test was used in three different scenarios:

- Point-wise anomaly detection (to test if the data point comes from a Student's t-distribution with known parameters)
- Segment-wise anomaly detection (compare means of values of two fragments of time series)
- To test abnormal slope of a linear model (for consumption sensor data)



Figure 2: Light sensor readings of a lamp

#### Fault detection models: KS-test

- If the nature of the data does not imply a normal distribution, the non-parametrical two-sample Kolmogorov-Smirnov test can be used.
- An example of that behavior would be air conditioner temperature and current measurements.



Figure 3: Temperature readings of an air conditioner

## Hidden Markov Model

- Hidden Markov model can be used to detect a change in hidden states (operating modes) of the analyzed system.
- In condition monitoring, hidden states refer to operating modes, including both correct and faulty modes.
- The forward-backward algorithm is used to calculate likelihood of a test signal, which is then used as an anomaly score.



Figure 4: HMM-based signal segmentation of a gas boiler temperature readings

## Results

- Proposed approach shows significant difference between correct and faulty operating modes on the training dataset.
- Obtained models are intended to be used as a theoretical basis for the design of industrial housing and utility condition monitoring systems.

Element type	Fault type	Fault symptoms	Model	Sensor	Criteria
Heater	thermostat failure	overheating	t-test	temperature	p-value <0.05
Power transformer	overload	overheating	t-test	current, temperature	p-value <0.05
Gas boiler	thermal overheating thermostat breakdown	overheating	t-test on HMM-generated likelihood values	temperature	p-value <0.05
Ventilation blower fan	clogging	increased consumption	t-test	airflow, vibration	p-value <0.05
	overload	unstable airflow	t-test	airflow	p-value <0.05
Air conditioner	freon leakage filter contamination	lack of cooling frosting and icing	KS-test	temperature	p-value <0.05 p-value <0.05
Water pump	sedimentation	decrease in pumping efficiency	linear regression	flow	slope p-value $< 0.05$
Lamp	flickering	lamp burnout	point-wise t-test	light	% of rejections $>20$

Table 1: Fault types and detection methods

# Thank you!

#### Statistical Fault Detection

- Student's t-test is used to calculate a deviation of the test data from that normal distribution. That allows us to set a 95% confidence interval to detect point anomalies in real-time situations. T-test is used in two scenarios: to detect point anomalies and to compare means of values of two fragments of time series, thereby to test a whole time series fragment for a fault occurrence.
- the two-sampled Kolmogorov-Smirnov test is a statistical nonparametric approach to determine if two samples have significantly different probability distributions. It is used to detect and classify faulty modes of operation of an air conditioner.
- **linear regression model** is a statistical approach to model the dependency of two variables with a linear function. It is applied in water pump consumption monitoring. During a fault detection phase, if a linear model of current operating mode has a significantly different slope from the trained model, the mode is considered faulty. A regression task is performed to calculate slopes and their standard errors, a z-test is performed to test the equality of slopes.

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